TLK 96 S

MICROPROCESSOR-BASED DIGITAL ELECTRONIC CONTROLLER

OPERATING INSTRUCTIONS

Vr. 00 (ENG) - cod.: ISTR 06826

FOREWORD

This manual contains the information necessary for the product to be installed correctly and also instructions for its maintenance and use; we therefore recommend that the utmost attention is paid to the following instructions.

Though this manual has been issued with the greatest care, will not take any responsibility deriving from its use.

The same applies to each person or Company involved in the issuing of this manual.

This document is the exclusive property of which forbids any reproduction and divulgation , even in part, of the document, unless expressly authorized.

reserves the right to make any formal or functional changes at any moment and without any notice.

INDEX

- 1 INSTRUMENT DESCRIPTION
- 1.1 GENERAL DESCRIPTION
- 1.2 FRONT PANEL DESCRIPTION
- 2 PROGRAMMING
- 2.1 FAST PROGRAMMING OF SET POINT
- 2.2 PARAMETER PROGRAMMING
- 3 INFORMATION ON INSTALLATION AND USE
- 3.1 PERMITTED USE
- 3.2 MECHANICAL MOUNTING
- 3.3 ELECTRICAL CONNECTIONS
- 3.4 ELECTRICAL WIRING DIAGRAM
- 4 FUNCTIONS
- 4.1 MEASURING AND VISUALIZATION
- 4.2 OUTPUTS CONFIGURATION
- 4.3 ON/OFF CONTROL
- 4.4 NEUTRAL ZONE ON/OFF CONTROL
- 4.5 SINGLE ACTION PID CONTROL
- 4.6 AUTO-TUNING FUNCTIONS
- 4.7 REACHING OF SET POINT AT CONTROLLED SPEED
- 5 PROGRAMMABLE PARAMETERS TABLE
- 6 PROBLEMS, MAINTENANCE AND GUARANTEE
- 6.1 ERROR SIGNALLING
- 6.2 CLEANING
- 6.3 GUARANTEE AND REPAIRS
- 7 TECHNICAL DATA
- 7.1 ELECTRICAL DATA
- 7.2 MECHANICAL DATA
- 7.3 MECHANICAL DIMENSIONS, PANEL CUT-OUT AND MOUNTING
- 7.4 FUNCTIONAL DATA
- 7.5 MEASUREMENT RANGE TABLE
- 7.6 INSTRUMENT ORDERING CODE

1 - INSTRUMENT DESCRIPTION

1.1 - GENERAL DESCRIPTION

TLK 96 S is a digital microprocessor-based controller, with ON/OFF, Neutral Zone ON/OFF, PID single action, PID dual action (direct and reverse) control and with **AUTO-TUNING FAST** function, **SELF-TUNING** function for PID control.

The process value is visualized on 4 red displays, while the output status is indicated by 2 LED displays.

The instrument is equipped with a 3 LED programmable shift indexes and can have up to 2 outputs: relay type or can drive solid state relays type (SSR).

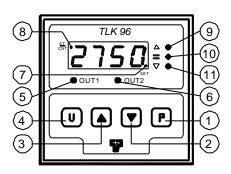
Depending on the model required the input accept:

- **C**: Thermocouples temperature probes (J,K,S and IRS Infrared sensors), mV signals (0..50/60 mV, 12..60 mV), Thermoresistances PT100.
- **E**: Thermocouples temperature probes (J,K,S and IRS Infrared sensors), mV signals (0..50/60 mV, 12..60 mV), Thermistors PTC and NTC.

I: normalized analogue signals 0/4..20 mA

V : normalized analogue signals 0..1 V, 0/1..5 V, 0/2..10 V

1.2 - FRONT PANEL DESCRIPTION



- **1 Key P**: This is used to access the programming parameters and to confirm selection.
- **2 Key DOWN**: This is used to decrease the values to be set and to select the parameters. If the key is held down, the user returns to the previous programming level until he exits the programming mode.
- **3 Key UP**: This is used to increase the values to be set and to select the parameters. If the key is held down, the user returns to the previous programming level until he exits the programming mode. Outside the programming mode it permits visualisation of the output control power.
- **4 Key U**: It can used to Activate Auto-tuning and Self-tuning functions and modify the visibility of the parameters in "ConF" menu (see par. 2.3).

5 - Led OUT1: indicates the state of output OUT1

- 6 Led OUT2 : indicates the state of output OUT2
- **7 Led SET**: It indicates access to the programming mode and parameter programming level.
- **8 Led AT/ST**: indicates that the Self-tuning function is activated (light on) or that Auto-tuning (flashing) is in progress.
- **9 Led Shift index:** indicates that the process value is lower than [SP1-AdE].
- **10 Led = Shift index:** indicates that the process value is within the range [SP1+AdE ... SP1-AdE]

11 - Led + Shift index: indicates that the process value is higher 3.1 - PERMITTED USE than [SP1+AdE].

2 - PROGRAMMING

2.1 - FAST PROGRAMMING OF THE SET POINT

This procedure permits rapid programming of the Set Point (SP1) and Set Point (SP2)

Push key "P", then release it and the display will visualise "SP 1" 3.2 - MECHANICAL MOUNTING alternatively to the programmed value.

To modify the value, press "UP" key to increase it or the "DOWN" key to decrease it.

These keys change the value one digit at a time but if they are pressed for more than one second, the value increases or decreases rapidly and, after two seconds in the same condition, to be reached rapidly.

alternatively to the programmed value.

To modify the value, press "UP" key to increase it or the "DOWN" key to decrease it.

These keys change the value one digit at a time but if they are pressed for more than one second, the value increases or decreases rapidly and, after two seconds in the same condition, the changing speed increases in order to allow the desired value to be reached rapidly.

To exit the fast Set programming it is necessary to push key P, after the visualisation of the last Set Point, or alternatively, if no key is pressed for approx. 15 seconds, the display will return to normal functioning automatically.

Set Point (SP1 and SP2) can be programmed with a value that is between the value programmed on par. "SPLL" and the one programmed on par. "SPHL".

2.2 - PARAMETERS PROGRAMMING

By pushing key "P" and holding it down for approx. 2 sec. it is possible to enter into the main selection menu.

Using the "UP" and "DOWN" keys, it is possible to select the desired parameter and, if the key "P" is pressed, the display will alternatively show the parameter's code and its programming value, which can be modified by using the "UP" or "DOWN" keys. Once the desired value has been programmed, push key "P" once more: the new value will be memorised and the display will show only the code of the selected parameter.

new parameter (if present) and modify it as described above.

To exit the programming mode, no key should be pressed for approx. 20 seconds, or keep the "UP" or "DOWN" pressed until exit cause damage to people, things or animals. from the programming mode is obtained.

3 - INFORMATION ON INSTALLATION AND USE

The instrument has been projected and manufactured as a measuring and control device to be used according to EN61010-1 for the altitudes operation until 2000 ms.

The use of the instrument for applications not expressly permitted by the above mentioned rule must adopt all the necessary protective measures.

The instrument CANNOT be used in dangerous environments (flammable or explosive) without adequate protection.

The installer must ensure that EMC rules are respected, also after the instrument installation, if necessary using proper filters.

Whenever a failure or a malfunction of the device may cause dangerous situations for persons, thing or animals, please remember that the plant has to be equipped with additional devices which will guarantee safety.

The instrument, in DIN case 96 x 96 mm, is designed for flush-in panel mounting.

Make a hole 90 x 90 mm and insert the instrument, fixing it with the provided special brackets.

We recommend that the gasket is mounted in order to obtain the front protection degree as declared. Avoid placing the instrument the changing speed increases in order to allow the desired value in environments with very high humidity levels or dirt that may create condensation or introduction of conductive substances into the instrument.

Push key "P", then release it and the display will visualise "SP 2" Ensure adequate ventilation to the instrument and avoid installation in containers that house devices which may overheat or which may cause the instrument to function at a higher temperature than the one permitted and declared.

> Connect the instrument as far away as possible from sources of electromagnetic disturbances such as motors, power relays, relays, solenoid valves, etc.

3.3 - ELECTRICAL CONNECTION

Carry out the electrical wiring by connecting only one wire to each terminal, according to the following diagram, checking that the power supply is the same as that indicated on the instrument and that the load current absorption is no higher than the maximum electricity current permitted.

As the instrument is built-in equipment with permanent connection inside housing, it is not equipped with either switches or internal devices to protect against overload of current: the installation will include an overload protection and a two-phase circuit-breaker, placed as near as possible to the instrument, and located in a position that can easily be reached by the user and marked as instrument disconnecting device which interrupts the power supply to the equipment.

It is also recommended that the supply of all the electrical circuits connected to the instrument must be protect properly, using devices (ex. fuses) proportionate to the circulating currents.

It is strongly recommended that cables with proper insulation, according to the working voltages and temperatures, be used.

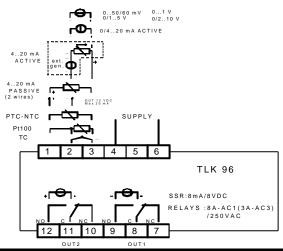
Furthermore, the input cable of the probe has to be kept separate from line voltage wiring. If the input cable of the probe is screened, it has to be connected to the ground with only one side.

By using the "UP" or "DOWN" keys, it is then possible to select a We recommend that a check should be made that the parameters are those desired and that the application functions correctly before connecting the outputs to the actuators so as to avoid malfunctioning that may cause irregularities in the plant that could

> and its legal representatives do not assume any responsibility for any damage to people, things or animals deriving from

violation, wrong or improper use or in any case not in If instead, it is desired that the offset set should not be constant for compliance with the instrument's features.

3.4 - ELECTRICAL WIRING DIAGRAM



4 - FUNCTIONS

4.1 - MEASURING AND VISUALIZATION

All the parameters referring measurements are contained in the group "InP".

Depending on the model required the input accept:

C: Thermocouples temperature probes (J,K,S and IRS Infrared (0..50/60)m۷ signals mV, 12..60 Thermoresistances PT100.

E: Thermocouples temperature probes (J,K,S and IRS Infrared sensors), mV signals (0..50/60 mV, 12..60 mV), Thermistors PTC

I: normalized analogue signals 0/4..20 mA

V: normalized analogue signals 0..1 V, 0/1..5 V, 0/2..10 V

Depending on the model, using par. "SEnS", it's possible to select the type of input probe, which can be:

- for thermocouples J (J), K (CrAL), S (S) or for infrared sensors serie IRTC1 with linearization J (Ir.J) or K (Ir.CA)
- for thermoresistances Pt100 IEC (Pt1) or thermistors PTC KTY81-121 (Ptc) or NTC 103AT-2 (ntc)
- for normalised signals in current 0..20 mA (0.20) or 4..20 mA
- for normalised signals in tension 0..1 V (0.1), 0..5 V (0.5), 1..5 V (1.5), 0..10 V (0.10) or 2..10 V (2.10).
- for normalised signals in tension 0..50 mV (0.50), 0..60 mV (0.60), 12..60 mV (12.60).

We recommend to switch on and off the instrument when these parameters are modified, in order to obtain a correct measuring. For the instruments with input for temperature probes (tc, rtd) it's possible to select, through par. "Unit", the unit of measurement (°C, °F) and, through par. "dP" (Pt100, PTC and NTC only) the desired resolution (0=1°; 1=0,1°).

Instead, with regards to the instruments with normalised analogue input signals, it is first necessary to program the desired resolution on par. "dP" (0=1; 1=0,1; 2=0,01; 3=0,001) and then, on par. "SSC", the value that the instrument must visualise at the beginning of the scale (0/4 mA, 0/12 mV, 0/1 V o 0/2 V) and, on par. "FSC", the value that the instrument must visualise at the end of the scale (20 mA, 50 mV, 60 mV, 5 V or 10 V).

The instrument allows for measuring calibration, which may be used to recalibrate the instrument according to application needs, by using par. "OFSt" and "rot".

Programming par. "rot"=1,000, in par. "OFSt" it is possible to set a positive or negative offset that is simply added to the value read by the probe before visualisation, which remains constant for all the measurements.

all the measurements, it is possible to operate the calibration on any two points.

In this case, in order to decide which values to program on par. "OFSt" and "rot", the following formulae must be applied:

"rot" = (D2-D1)/(M2-M1)"OFSt" = D2 - ("rot" x M2) where:

M1 =measured value 1

D1 = visualisation value when the instrument measures M1

M2 =measured value 2

D2 = visualisation value when the instrument measures M2

It then follows that the instrument will visualise:

DV = MV x "rot" + "OFSt"

where: DV = visualised value MV= measured value

Example 1: It is desired that the instrument visualises the value effectively measured at 20° but that, at 200°, it visualises a value lower than 10° (190°).

Therefore: M1=20; D1=20; M2=200; D2=190

"rot" = (190 - 20) / (200 - 20) = 0.944"OFSt" = 190 - (0,944 x 200) = 1,2

Example 2: It is desired that the instrument visualises 10° whilst the value actually measured is 0°, but, at 500° it visualises a 50° higher value (550°).

Therefore: M1=0; D1=10; M2=500; D2=550

"rot" = (550 - 10) / (500 - 0) = 1,08"OFSt" = 550 - (1,08 x 500) = 10

By using par. "FiL" it is possible to program time constant of the software filter for the input value measured, in order to reduce noise sensitivity (increasing the time of reading).

In case of measurement error, the instrument supplies the power as programmed on par. "OPE".

This power will be calculated according to cycle time programmed for the PID controller, while for the ON/OFF controllers the cycle time is automatically considered to be equal to 20 sec. (e.g. In the event of probe error with ON/OFF control and "OPE"=50, the control output will be activated for 10 sec., then it will be deactivated for 10 sec. and so on until the measurement error remains.).

In the group "PAn" the par. "AdE" is present that defines the 3 led shift index functioning.

The lighting up of the green led = indicates that the process value is within the range [SP1+AdE ... SP1-AdE], the lighting up of the led - indicates that the process value is lower than [SP1-AdE] and the lighting up of the led + indicates that the process value is higher than [SP1+AdE].

4.2 - OUTPUTS CONFIGURATION

The instrument's outputs can be programmed by entering the group of parameters "Out, where the relative parameters "O1F" and "O2F" (depending on the number of outputs available on the instrument) are located.

The outputs can be set for the following functions:

- Main control output (1.rEG)
- Secondary control output (2.rEG)
- Alarm output normally open (ALno)
- Alarm output normally closed (ALnc)
- Alarm output normally closed with led reverse indication (ALni)
- Output deactivated (OFF)

The coupling outputs number outputs - number alarms can be made in the group referring to the alarm to the alarm ("IAL1").

4.3 - ON/OFF CONTROL (.1rEG)

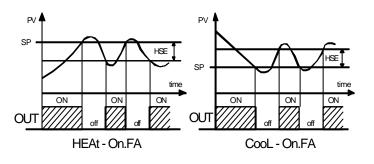
All the parameters referring to the ON/OFF control are contained in the group "IrEG".

This type of control can be obtained by programming par. "Cont" = On.FS or = On.FA and works on the output programmed as 1.rEG, depending on the measure, on the Set Point "SP1", on the This function allows a control by time on the output 2.rEG functioning mode "Func" and on the hysteresis "HSEt".

The instrument carries out an ON/OFF control with symmetric hysteresis if "Cont" = On.FS or with asymmetrical hysteresis if "Cont" = On.FA.

The control works in the following way: in the case of reverse action, or heating ("FunC"=HEAt), it deactivates the output, when the process value reaches [SP1 + HSEt] in case of symmetrical hysteresis, or [SP1] in case of asymmetrical hysteresis and is then activated again when the process value goes below value [SP1 - HSEt].

Vice versa, in case of direct action or cooling ("Func"=CooL), it The function is not active programming "CPdt" =OFF. deactivates the output, when the process value reaches [SP1 -HSEt] in case of symmetrical hysteresis, or [SP1] in case of activation delay, caused by "Compressor Protection" function. asymmetrical hysteresis and is activated again when the process value goes above value [SP1 + HSEt].



4.4 - NEUTRAL ZONE ON/OFF CONTROL (1.rEG - 2.rEG)

All the parameters referring to Neutral Zone ON/OFF control are contained in the group "IrEG".

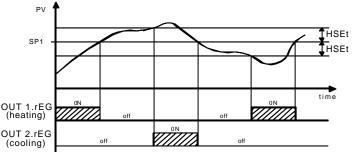
This type of control can be obtained when 2 outputs are programmed respectively as 1.rEG and 2.rEG and the par. "Cont" = nr.

The Neutral Zone control is used to control plants in which there is humidifier, etc.) and an element which causes a negative increase following parameters: (ex. Cooler, de-humidifier, etc).

The control functions works on the programmed outputs depending on the measurement, on the Set Point "SP1" and on the hysteresis "HSEt".

The control works in the following way: it deactivates the outputs when the process value reaches the Set Point and it activates the output 1.rEG when the process value goes below value [SP1 -HSEt], or it activates the output 2.rEG when the process value of the process or at the changing of the Set Point to be avoided. goes above [SP1 + HSEt].

Consequently, the element causing a positive increase has to be connected to the output programmed as 1.rEG while the element causing a negative increase has to be connected to the output programmed as 2.rEG.



If 2.rEG output is used to control compressor is possible to use 4.6 - AUTOTUNING FUNCTIONS the "Compressor Protection" function that has the meaning to All the parameters referring to the AUTO-TUNING and SELFavoid compressor "short cycles".

activation, independently by the temperature control request.

The protection is a "delayed after deactivation" type.

This protection permits to avoid the output activation for a time programmable on par. CPdt" (expressed in sec.); the output activation will occurs only after the elapsing of time "CPdt".

The time programmed on parameter "CPdt" is counted starting from the last output deactivation.

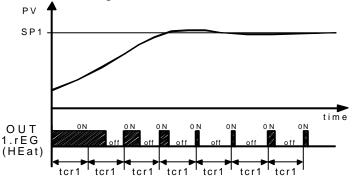
Obviously, whether during the time delay caused by the compressor protection function, the regulator request should stop. the output activation foreseen after time "CPdt" would be erased.

The led relative to 2.rEG output blinks during the phases of output

4.5 - SINGLE ACTION PID CONTROL (1.rEG)

All the parameters referring to PID control are contained in the group "lrEG".

The Single Action PID control can be obtained by programming par. "Cont" = Pid and works on the output 1.rEG depending on the Set Point "SP1", on the functioning mode "Func" and on the instrument's PID algorithm.



In order to obtain good stability of the process variable, in the event of fast processes, the cycle time "tcr1" has to have a low value with a very frequent intervention of the control output.

In this case use of a solid state relay (SSR) is recommended for driving the actuator.

an element which causes a positive increase (ex. Heater, The Single Action PID control algorithm foresees the setting of the

"Pb" - Proportional Band

"tcr1" - Cycle time of the output 1.rEG

"Int" - Integral Time

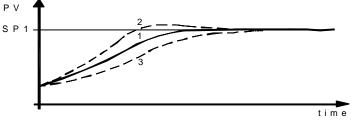
"rS" - Manual Reset (if "Int =0 only)

"dEr" - Derivative Time

"FuOC" - Fuzzy Overshoot Control

This last parameter allows the variable overshoots at the start up

Please remember that a low value on this parameter reduces the overshoot while a high value increase it.



1: Value "FuOC" OK

2: Value "FuOC" too high

3: Value "FuOC" too low

TUNING functions are contained in the group "IrEG".

The AUTO-TUNING and SELF-TUNING functions permit the 4.7 - REACHING OF THE SET POINT AT CONTROLLED SPEED automatic tuning of the PID controller.

The **AUTO-TUNING** function permits the calculation of the PID parameters by means of a FAST type tuning cycle and, at the end of this operation, the parameters are stored into the instrument's memory and remain constant during control.

The **SELF-TUNING** function (rule based "TUNE-IN") instead allows control monitoring and the continuous calculation of the parameters during control.

Both functions automatically calculate the following parameters:

"Pb" - Proportional Band

"tcr1" - Cycle time of the output 1.rEG

"Int" - Integral Time

"dEr" - Derivative Time

"FuOC" - Fuzzy Overshoot Control

To activate the AUTO-TUNING function proceed as follows:

- 1) Program and activate the desired Set Point.
- 2) Program par. "Cont" =Pid.
- 3) Program par. "Func" according to the process to be controlled through output 1.rEG.
- 4) Program an output as 2.rEG if the instrument controls a plant with double action
- 5) Program par. "Auto" as:
- "1" if auto-tuning is desired automatically, each time the instrument is switched on, on the condition that the process value is lower (with "Func" =HEAt) than [SP- |SP/2|] or higher (with "Func" =CooL) than [SP+ |SP/2|].
- "2" if auto-tuning is desired automatically, the next time the instrument is switched on, on the condition that the process value is lower (with "Func" =HEAt) than [SP- |SP/2|] or higher (with "Func" =CooL) than [SP+ |SP/2|], and once the tuning is finished, the par. "Auto" is automatically swapped to the OFF state
- "3" if manual auto-tuning is desired, by key "U". The Autotuning will start at the condition that the process value is lower (with "Func" =HEAt) than [SP- |SP/5|] or higher (with "Func" =CooL) than [SP+ |SP/5|].
- "4" if it's desired to activate the autotuning automatically to every change of Set Point. The Autotuning will start at the condition that the process value is lower (with "Func" =HEAt) than [SP- |SP/5|] or higher (with "Func" =CooL) than [SP+ |SP/5|].
- 6) Exit from the parameter programming.
- 7) Connect the instrument to the controlled plant.
- 8) Activate the Auto-tuning by key U if "Auto" = 3 or switch off and then on the instrument if "Auto" = 1 or 2.

At this point the Auto-tuning function is activated and is indicated by the flashing led AT/ST.

The regulator carries out several operations on the connected plant in order to calculate the most suitable PID parameters.

If, at the Auto-tuning start, the condition for the lower or higher process value is not found the display will show "ErAt" and the instrument will be swapped to normal control conditions according to the previously programmed parameters.

To make the error "ErAt" disappear, press key P.

The Auto-tuning cycle duration has been limited to 12 hours maximum.

If Auto-tuning is not completed within 12 hours, the instrument will show "noAt" on the display.

In case of probe error, the instrument automatically stops the cycle

The values calculated by Auto-tuning are automatically stored in the instrument's memory at the end of the correct PID parameters

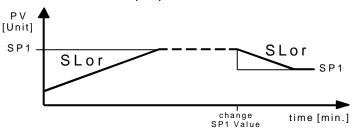
If the instrument is switched off during Auto-tuning function activated, these functions will remain activated the next time it is switched on.

All the parameters referring to the ramps functioning are contained in the group "1rEG".

It is possible to reach the set point in a predetermined time (in any case longer than the time the plant would naturally need). This could be useful in those processes (heating or chemical treatments, etc.) where the set point has to be reached gradually, in a predetermined time.

The function is determined by the following parameter:

"SLor" - Gradient of ramp expressed in unit/minute



Example with start from values lower than SP 1 and with decreasing of SP 1.

P.A.: In case of PID control, if Auto-tuning is desired whilst the ramp function is active, this will not be carried out until the tuning cycle has been completed.

It is therefore recommended that Auto-tuning be started avoiding activating the ramp function and, once the tuning is finished, deactivate Auto-tuning ("Auto" = OFF), program the desired ramp and, if it automatic tuning is desired, enable the Self-tuning function.

5 - PROGRAMMABLE PARAMETERS TABLE

Here following are described all the parameters available on the instrument. Some of them could be not present or because they are depending on the type of instrument or because they are automatically disabled as unnecessary.

	Par.		Description	Range	Def.	Note
ĺ	1	SP1L	Low Set Point 1	-1999 ÷	-1999	
				SPH1		
	2	SP1H	High Set Point 1	SPL1 ÷ 9999	9999	
ĺ	3	SP2L	Low Set Point 2	-1999 ÷	-1999	
				SPH2		
	4	SP2H	High Set Point 2	SPL2 ÷ 9999	9999	
ĺ	5	SP2C	in=independent	in / di	in	
		di=SP2 relative to SP1				
	6	SP1	Set Point 1	SPLL ÷ SPHL	0	
	7	SP2	Set Point 2	SPLL ÷ SPHL	0	

			1		
8	SEnS	Probe type:	input C :	J	
		J= thermocoupled J	J/CrAL/S/		
		CrAL= termocoupled K	Ir.J / Ir.CA /		
		S= thermocoupled S	Pt1 / 0.50 /		
		Ir.J= Infrared Sen. IRS J	0.60 / 12.60		
		Ir.CA= Infrared Sen. IRS	input E :	Ptc	
		K	J/ CrAL/S/	110	
		1.,			
		Pt1= thermoresistance	Ir.J / Ir.CA /		
		Pt100	Ptc / ntc /		
		0.50= 050 mV	0.50 / 0.60 /		
		0.60= 060 mV	12.60		
		12.60= 1260 mV	input I :	4.20	
		Ptc= thermistor PTC	0.20 / 4.20		
		KTY81-121	input V :	0.10	
		ntc= thermistor NTC	0.1 / 0.5 / 1.5 /		
		103-AT2	0.10 / 2.10		
		0.20= 020 mA	0.107 2.10		
		4.20= 420 mA			
		0.1= 01 V			
		0.5=05 V			
		1.5= 15 V			
		0.10= 010 V			
		2.10= 210 V			
9	SSC	Low scale limit in case	-1999 ÷ FSC	0	
		of input with V / I			
		signals			
10	FSC	High scale limit in case	SSC ÷ 9999	100	
'	. 55	of input with V / I	200.0000	.00	
		signals			
4.4	40		D+1 / D+a / =+==		
11	dP	Number of decimal	Pt1 / Ptc / ntc:	0	
		figures	0/1		
1			norm sig.:		
			0 ÷ 3		
12	Unit	Temperature unit of	0÷3 °C/°F	°C	
12	Unit	Temperature unit of measurement	0÷3 °C/°F	°C	
12	Unit		0 ÷ 3 °C / °F 0FF÷ 20.0	°C	
		measurement	°C/°F		
	FiL	measurement Input digital filter	°C / °F 0FF÷ 20.0 sec.	1.0	
13 14	FiL OFSt	measurement Input digital filter Measuring Offset	°C / °F 0FF÷ 20.0 sec. -1999÷ 9999	1.0	
13	FiL OFSt	measurement Input digital filter Measuring Offset Rotation of the	°C / °F 0FF÷ 20.0 sec.	1.0	
13 14 15	FiL OFSt rot	measurement Input digital filter Measuring Offset	°C / °F 0FF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000	1.0 0 1.000	
13 14	FiL OFSt	measurement Input digital filter Measuring Offset Rotation of the	°C / °F 0FF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59	1.0	
13 14 15	FiL OFSt rot ton1	measurement Input digital filter Measuring Offset Rotation of the	°C / °F 0FF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec	1.0 0 1.000 OFF	
13 14 15	FiL OFSt rot	measurement Input digital filter Measuring Offset Rotation of the	°C / °F 0FF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59	1.0 0 1.000	
13 14 15	FiL OFSt rot ton1	measurement Input digital filter Measuring Offset Rotation of the	°C / °F 0FF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec	1.0 0 1.000 OFF	
13 14 15	FiL OFSt rot ton1	measurement Input digital filter Measuring Offset Rotation of the	°C / °F 0FF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59	1.0 0 1.000 OFF	
13 14 15 16	FiL OFSt rot ton1 toF1	measurement Input digital filter Measuring Offset Rotation of the	°C / °F 0FF÷ 20.0 sec1999÷ 9999 0.000÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec	1.0 0 1.000 OFF	
13 14 15 16	FiL OFSt rot ton1 toF1 ton2	measurement Input digital filter Measuring Offset Rotation of the	°C / °F OFF÷ 20.0 sec1999÷ 9999 0.000÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec	1.0 0 1.000 OFF	
13 14 15 16 17	FiL OFSt rot ton1 toF1	measurement Input digital filter Measuring Offset Rotation of the	°C / °F OFF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59	1.0 0 1.000 OFF OFF	
13 14 15 16 17 18	FiL OFSt rot ton1 toF1 ton2	measurement Input digital filter Measuring Offset Rotation of the measuring straight line	°C / °F OFF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec	1.0 0 1.000 OFF OFF OFF	
13 14 15 16 17	FiL OFSt rot ton1 toF1 ton2	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type:	°C / °F OFF÷ 20.0 sec1999÷ 9999 0.000÷ 2.000 OFF / 99.59 min.sec	1.0 0 1.000 OFF OFF	
13 14 15 16 17 18	FiL OFSt rot ton1 toF1 ton2	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID	°C / °F OFF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec	1.0 0 1.000 OFF OFF OFF	
13 14 15 16 17 18	FiL OFSt rot ton1 toF1 ton2	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym.	°C / °F OFF÷ 20.0 sec1999÷ 9999 0.000÷ 2.000 OFF / 99.59 min.sec	1.0 0 1.000 OFF OFF OFF	
13 14 15 16 17 18	FiL OFSt rot ton1 toF1 ton2	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym. nr= ON/OFF Neutral	°C / °F OFF÷ 20.0 sec1999÷ 9999 0.000÷ 2.000 OFF / 99.59 min.sec	1.0 0 1.000 OFF OFF OFF	
13 14 15 16 17 18 19	FiL OFSt rot ton1 toF1 ton2 toF2 Cont	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym. nr= ON/OFF Neutral Zone	°C / °F OFF÷ 20.0 sec1999÷ 9999 0.000÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 90.59 min.sec	1.0 0 1.000 OFF OFF OFF Pid	
13 14 15 16 17 18	FiL OFSt rot ton1 toF1 ton2	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym. nr= ON/OFF Neutral Zone Functioning mode	°C / °F OFF÷ 20.0 sec1999÷ 9999 0.000÷ 2.000 OFF / 99.59 min.sec	1.0 0 1.000 OFF OFF OFF	
13 14 15 16 17 18 19 20	FiL OFSt rot ton1 toF1 ton2 toF2 Cont	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym. nr= ON/OFF Neutral Zone Functioning mode output 1	°C / °F OFF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec HEAt / CooL	1.0 0 1.000 OFF OFF OFF HEAt	
13 14 15 16 17 18 19	FiL OFSt rot ton1 toF1 ton2 toF2 Cont	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym. nr= ON/OFF Neutral Zone Functioning mode	°C / °F OFF÷ 20.0 sec1999÷ 9999 0.000÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 90.59 min.sec	1.0 0 1.000 OFF OFF OFF Pid	
13 14 15 16 17 18 19 20	FiL OFSt rot ton1 toF1 ton2 toF2 Cont	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym. nr= ON/OFF Neutral Zone Functioning mode output 1	°C / °F OFF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec HEAt / CooL	1.0 0 1.000 OFF OFF OFF HEAt	
13 14 15 16 17 18 19 20	FiL OFSt rot ton1 toF1 ton2 toF2 Cont	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym. nr= ON/OFF Neutral Zone Functioning mode output 1 Functioning mode output 2	°C / °F OFF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec HEAt / CooL	1.0 0 1.000 OFF OFF OFF HEAt	
13 14 15 16 17 18 19 20 21 22	FiL OFSt rot ton1 toF1 ton2 toF2 Cont Fun1 Fun2	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym. nr= ON/OFF Neutral Zone Functioning mode output 1 Functioning mode	°C / °F OFF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 90.59 min.sec HEAt / CooL HEAt / CooL	1.0 0 1.000 OFF OFF OFF HEAt HEAt	
13 14 15 16 17 18 19 20 21 22 23	FiL OFSt rot ton1 toF1 ton2 toF2 Cont Fun1 Fun2 HSE1	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym. nr= ON/OFF Neutral Zone Functioning mode output 1 Functioning mode output 2 Hysteresis of ON/OFF control	°C / °F OFF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec Pid / On.FA / nr HEAt / CooL HEAt / CooL 0 ÷ 9999	1.0 0 1.000 OFF OFF OFF Pid HEAt HEAt 1	
13 14 15 16 17 18 19 20 21 22	FiL OFSt rot ton1 toF1 ton2 toF2 Cont Fun1 Fun2	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym. nr= ON/OFF Neutral Zone Functioning mode output 1 Functioning mode output 2 Hysteresis of ON/OFF control Hysteresis of ON/OFF	°C / °F OFF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 90.59 min.sec HEAt / CooL HEAt / CooL	1.0 0 1.000 OFF OFF OFF HEAt HEAt	
13 14 15 16 17 18 19 20 21 22 23 24	FiL OFSt rot ton1 toF1 ton2 toF2 Cont Fun1 Fun2 HSE1 HSE2	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym. nr= ON/OFF Neutral Zone Functioning mode output 1 Functioning mode output 2 Hysteresis of ON/OFF control	°C / °F OFF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec HEAt / CooL HEAt / CooL 0 ÷ 9999 0 ÷ 9999	1.0 0 1.000 OFF OFF OFF Pid HEAt HEAt 1 1	
13 14 15 16 17 18 19 20 21 22 23	FiL OFSt rot ton1 toF1 ton2 toF2 Cont Fun1 Fun2 HSE1	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym. nr= ON/OFF Neutral Zone Functioning mode output 1 Functioning mode output 2 Hysteresis of ON/OFF control Hysteresis of ON/OFF control Compressor Protection	°C / °F OFF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec HEAt / CooL HEAt / CooL 0 ÷ 9999 0 ÷ 9999 OFF÷ 99.59	1.0 0 1.000 OFF OFF OFF Pid HEAt HEAt 1	
13 14 15 16 17 18 19 20 21 22 23 24 25	FiL OFSt rot ton1 toF1 ton2 toF2 Cont Fun1 Fun2 HSE1 HSE2 Ptd1	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym. nr= ON/OFF Neutral Zone Functioning mode output 1 Functioning mode output 2 Hysteresis of ON/OFF control Hysteresis of ON/OFF control Compressor Protection time for OUT1	°C / °F OFF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec HEAt / CooL HEAt / CooL 0 ÷ 9999 OFF÷ 99.59 min.sec	1.0 0 1.000 OFF OFF OFF Pid HEAt HEAt 1 1 OFF	
13 14 15 16 17 18 19 20 21 22 23 24	FiL OFSt rot ton1 toF1 ton2 toF2 Cont Fun1 Fun2 HSE1 HSE2	measurement Input digital filter Measuring Offset Rotation of the measuring straight line Control type: Pid= PID On.FA= ON/OFF asym. nr= ON/OFF Neutral Zone Functioning mode output 1 Functioning mode output 2 Hysteresis of ON/OFF control Hysteresis of ON/OFF control Compressor Protection	°C / °F OFF÷ 20.0 sec1999 ÷ 9999 0.000 ÷ 2.000 OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec OFF / 99.59 min.sec HEAt / CooL HEAt / CooL 0 ÷ 9999 0 ÷ 9999 OFF÷ 99.59	1.0 0 1.000 OFF OFF OFF Pid HEAt HEAt 1 1	

27	27 PtS1 Compressor Protection		OFF÷ 99.59	OFF	
		time for OUT1	min.sec		
28	PtS2	Compressor Protection	OFF÷ 99.59	OFF	
		time for OUT2	min.sec		
		Delay at power on	OFF ÷ 99.59	OFF	
			min.sec		
30 Auto		Autotuning Fast enable	OFF /	OFF	
		OFF = Not active	1/2/3/4		
		1 = Start each power on			
		2= Start at first power			
		on			
		3= Start manually			
		4= Start at change Set			
31	Pb	Proportional band	0 ÷ 9999	40	
32	Int	Integral time	OFF ÷ 9999	300	
			sec.		
33	dEr	Derivative time	OFF÷ 9999	30	
	Jenvanie imie		sec.		
34	FuOc	Fuzzy overshoot control	$0.00 \div 2.00$	0.50	
35	tcr1	Cycle time of output	0.1 ÷ 130.0	20.0	
		1.rEG	sec.		
36	rS	Manual reset	-100.0÷100.0	0.0	
			%		
37	SLor	Gradient of ramp:	$0.00 \div 99.99$	InF	
		InF= Ramp not active	/ InF unit/min.		
38	AdE	Shift value for the shift	OFF9999	5	
	index functioning				
39	PASS	Access Password to	OFF ÷ 9999	OFF	
		parameter functions			
40	r.PAS		-19999999		

6 - PROBLEMS, MAINTENANCE AND GUARANTEE

6.1 - ERROR SIGNALLING

ENTON GIONALLING				
Error	Reason	Action		
	Probe interrupted	Verify the correct		
uuuu	The measured variable is under the probe's limits (under-range)	connection between probe and instrument and then verify the correct functioning of the probe		
0000	The measured variable is over the probe's limits (over-range)			
ErAt	Auto-tuning not possible because the process value is too higher or too lower	Push key "P" in order to make the error message disappear. Once the error has been found, try to repeat the auto-tuning.		
noAt	Auto-tuning not finished within 12 hours	Check the functioning of probe and actuator and try to repeat the autotuning.		
ErEP	Possible anomaly of the EEPROM memory	Push key "P"		

In error conditions, the instrument provides an output power as programmed on par "OPE" and activates the alarm, if the relative parameter "AL1i" have been programmed = yES.

6.2 - CLEANING

We recommend cleaning of the instrument with a slightly wet cloth using water and not abrasive cleaners or solvents which may damage the instrument.

6.3 - GUARANTEE AND REPAIRS

The instrument is under warranty against manufacturing flaws or faulty material, that are found within 12 months from delivery date.

The guarantee is limited to repairs or to the replacement of the instrument. The eventual opening of the housing, the violation of the instrument or the improper use and installation of the product will bring about the immediate withdrawal of the warranty's effects. In the event of a faulty instrument, either within the period of warranty, or further to its expiry, please contact our sales department to obtain authorisation for sending the instrument to our company. The faulty product must be shipped to with a detailed description of the faults found, without any fees or charge for, except in the event of alternative agreements.

7 - TECHNICAL DATA

7.1 – ELECTRICAL DATA

Power supply: 24 VAC/VDC, 100.. 240 VAC +/- 10%

Frequency AC: 50/60 Hz

Power consumption: 5 VA approx.

<u>Input/s:</u> 1 input for temperature probes: tc J,K,S; infrared sensors IRS J e K; RTD Pt 100 IEC; PTC KTY 81-121 (990 Ω @ 25 °C); NTC 103AT-2 (10K Ω @ 25 °C) or mV signals 0...50 mV, 0...60 mV, 12 ...60 mV or normalized signals 0/4...20 mA, 0..1 V, 0/1...5 V, 0/2...10 V.

Normalized signals input impedance: 0/4..20 mA: 51 Ω ; mV and $V: 1 M\Omega$

Output/s: Up to 2 outputs. Relay SPDT-NO (8 A-AC1, 3 A-AC3 / 250 VAC); or in tension to drive SSR (8mA/8VDC).

Auxiliary supply output: 12 VDC / 20 mA Max.

Electrical life for relay outputs: 100000 operat.

Installation category: II Measurement category: I

Protection class against electric shock: Class II for Front panel Insulation: Reinforced insulation between the low voltage part (power supply and relay outputs) and front panel; Reinforced insulation between the low voltage section (Supply and relay outputs) and the extra low voltage section (input, SSR outputs); Reinforced between power supply and relays; No insulation between input and SSR outputs.

MECHANICAL DATA

Housing: Self-extinguishing plastic, UL 94 V0 Dimensions: 96 x 96 mm DIN, depht 73 mm

Weight: 215 g approx.

Mounting: Flush in panel in 90 x 90 mm hole

Connections: extractable 2,5 mm² screw terminal block

Degree of protection of front panel: IP 54 mounted in panel with gasket

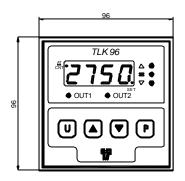
Pollution situation: Normal

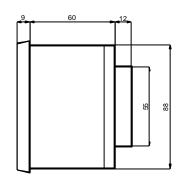
Operating temperature: 0 ... 50 °C

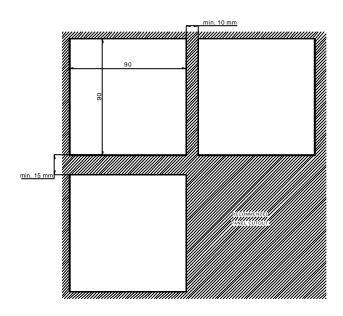
Operating humidity: 30 ... 95 RH% without condesation

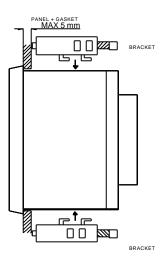
Storage temperature: -10 ... +60 °C

7.3 - MECHANICAL DIMENSIONS, PANEL CUT-OUT AND directive LV 73/23 and 93/68 (EN 61010-1) MOUNTING [mm]









7.4 - FUNCTIONAL FEATURES

Control: ON/OFF, Neutral Zone, PID

Measurement range: according to the used probe (see range table)

Display resolution: according to the probe used 1/0,1/0,01/0,001

Overall accuracy: +/- 0,5 % fs (+/- 1% for tc S)

Max cold junction compensation drift (in tc): 0,1 °C/°C with operating temperature 0 ... 50 °C after warm-up of 20 min.

Sampling rate: 130 ms.

Display: 4 Digit Red h 12 mm

Compliance: ECC directive EMC 89/336 (EN 61326), ECC

7.5 - MEASURING RANGE TABLE

INPUT	"dP" = 0	"dP"= 1, 2, 3
tc J	0 1000 °C	
"SEnS" = J	32 1832 °F	
tc K	0 1370 °C	
"SEnS" = CrAI	32 2498 °F	
tc S	0 1760 °C	
"SEnS" = S	32 3200 °F	
Pt100 (IEC)	-200 850 °C	-199.9 850.0 °C
"SEnS" = Pt1	-328 1562 °F	-199.9 999.9 °F
PTC (KTY81-121)	-55 150 °C	-55.0 150.0 °C
"SEnS" = Ptc	-67 302 °F	-67.0302.0 °F
NTC (103-AT2)	-50 110 °C	-50.0 110.0 °C
"SEnS" = ntc	-58 230 °F	-58.0 230.0 °F
020 mA		
"SEnS" = 0.20		
420 mA		
"SEnS" = 4.20		
0 50 mV		
"SEnS" = 0.50		
0 60 mV		
"SEnS" = 0.60		-199.9 999.9
12 60 mV	4000 0000	40.00 00.00
"SEnS" = 12.60	-1999 9999	-19.99 99.99
0 1 V		-1.999 9.999
"SEnS" = 0.1		-1.999 9.999
0 5 V		
"SEnS" = 0.5		
1 5 V		
"SEnS" = 1.5		
0 10 V		
"SEnS" = 0.10		
2 10 V		
"SEnS" = 2.10		

7.6 - INSTRUMENT ORDERING CODE

TLK 96 a b c d ee S

a: POWER SUPPLY

L = 24 VAC/VDC

H = 100... 240 VAC

b: INPUT

C = thermocouples (J, K, S, I.R), mV, thermoresistances (Pt100)

E = thermocouples (J, K, S, I.R.), mV, thermistors (PTC, NTC)

I = normalized signals 0/4..20 mA

V = normalized signals 0..1 V, 0/1..5 V, 0/2..10 V.

c: OUTPUT OUT1

R = Relay

 $\mathbf{O} = VDC$ for SSR

d: OUTPUT OUT2

R = Relay

 $\mathbf{O} = \mathsf{VDC}$ for SSR

- = None

ee: SPECIAL CODES